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...extension.h script for all characters has been done. The present invention relates to an electric power steering apparatus which can detect or determine a position of an electric power steering apparatus for a vehicle by a magnetically detecting a hall device provided on a power steering shaft of the vehicle by the use of a magnetic force. In a conventional electric power steering apparatus, when the rotation of a steering wheel of a vehicle is detected, a current flowing through a power steering motor is controlled based on the detected rotation, whereby a steering shaft connected to the steering wheel is driven. As a method of detecting the rotation of the steering wheel, for example, there is a method in which a magnet is attached to the periphery of the steering wheel, and the rotation of the steering wheel is detected by detecting a magnetic force of the magnet. When the steering wheel is rotated, the current flowing through the power steering motor changes in proportion to the rotation angle of the steering wheel, whereby the electric power of the power steering motor is applied to the wheels, or the like, through a power transmission device such as a rack and pinion mechanism. However, in the above-mentioned method, the magnet must be attached to the periphery of the steering wheel, so that the number of man-hours for manufacturing the electric power steering apparatus increases. Further, a position detecting unit must be mounted to the steering wheel and the rotation of the steering wheel must be detected by the position detecting unit. Therefore, the steering wheel is limited in shape and the unit becomes large in size, and there arises a problem in that the steering wheel becomes heavy. Therefore, it is desirable that the rotation of the steering wheel be detected or determined by the use of a magnetic force without using the magnet. As a conventional method of detecting or determining the rotation of the steering wheel by the use of the magnetic force, for example, there is a method in which a plurality of magnetic bodies are arranged along a direction in which the steering wheel is rotated, and a rotational position of the steering wheel is detected by the phase difference between the magnetic bodies. In this method, a magnet is not required, and therefore, the manufacturing cost is low, and the size of the apparatus can be made small. However, in this method, the magnetic bodies must be arranged along a direction in which the steering wheel is rotated, and a sensor for detecting a magnetic force is also required. Therefore, a problem arises in that the size of the apparatus is increased. Further, since the sensor 82157476af

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